

OBSOLETE - PART DISCONTINUED

Description

The ZMY20 is an extremely sensitive magnetic sensor employing the magneto-resistive effect of thin film permalloy. It allows the measurement of magnetic fields or the detection of magnetic parts. The highly sensitive and small size magnetoresistive sensors consist of a chip covered with thin film permalloy stripes. These stripes form a Wheatstone bridge, whose output voltage is proportional to the magnetic field component H_y . A perpendicular field H_x is necessary to stabilize sensor operation. This can be done by using a small permanent magnet.

Features

- Output voltage proportional to magnetic field H_y
- Adjustment of sensitivity and suppression of hysteresis by the auxiliary magnetic field H_x
- Magnetic fields vertical to the chip level are not effective
- **For automotive applications requiring specific change control (i.e. parts qualified to AEC-Q100/101/200, PPAP capable, and manufactured in IATF 16949 certified facilities), please [contact us](mailto:contact@diodes.com) or your local Diodes representative. <https://www.diodes.com/quality/product-definitions/>**

Applications

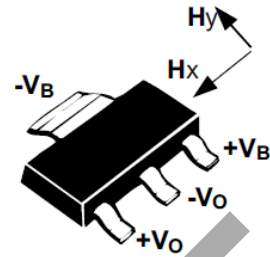
- Linear position sensors for process control, door interlocks, proximity detectors, machine tool sensing
- Scalar measurement for compassing
- Automotive - door switches, engine position and speed sensing
- Metering of fluids by sensing rotation of impeller
- Traffic counting and vehicle-type sensing
- Measurement of current in a conductor without connection

Ordering Information

DEVICE	REEL SIZE	TAPE WIDTH	QUANTITY PER REEL
ZMY20TA	7"	12mm	1000 units
ZMY20TC	13"	12mm	4000 units

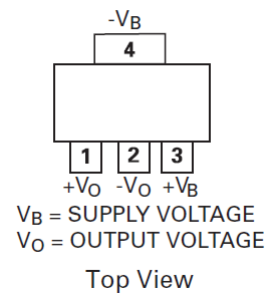
Marking Information

- ZMY20



SOT223S

PINOUT



Absolute Maximum Ratings

PARAMETER	SYMBOL	LIMIT	UNIT
Supply Voltage	V_B	12	V
Total power dissipation	P_{TOT}	120	mW
Operating Temperature Range	T_{amb}	-40 to +150	°C
Storage Temperature Range	T_{stg}	-65 to +150	°C

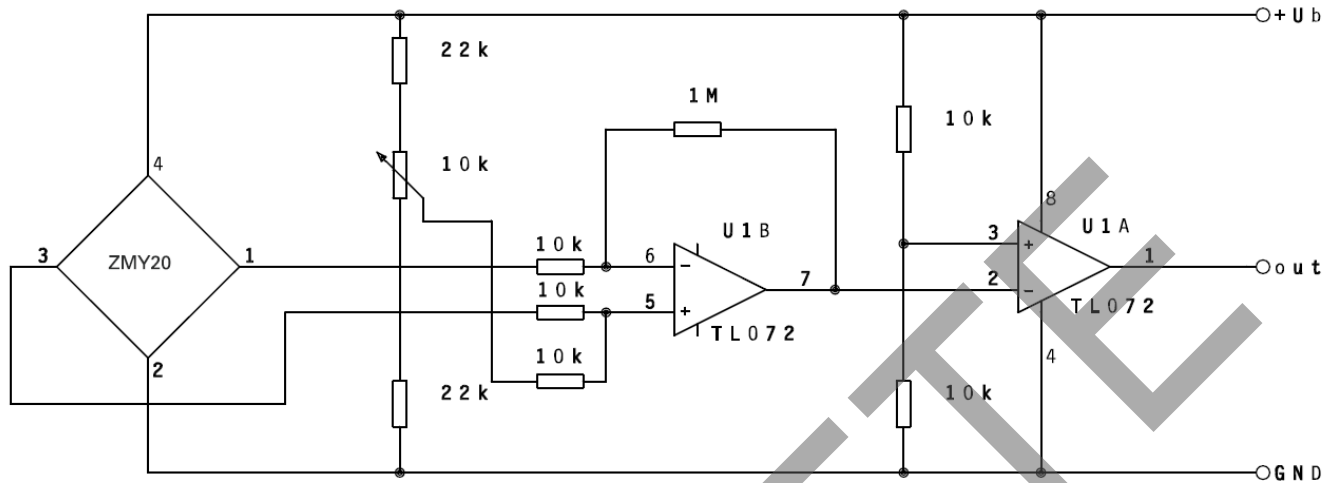
Electrical Characteristics (@ $T_A = +25^\circ\text{C}$ and $H_x = 3\text{kA/m}$, unless otherwise stated.)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNIT	TEST CONDITIONS
Bridge resistance	R_{br}	1.2	1.7	2.2	k Ω	
Output voltage range	V_O/V_B	16	20	24	mV/V	
Open circuit sensitivity	S	3.7	4.7	5.7	(mV/V)/(kA/m)	No disturbing field H_d allowed
Hysteresis of output voltage	V_{OH}/V_B	-	-	50	$\mu\text{V/V}$	$H_y \leq 2\text{kA/m}$
Offset Voltage	V_{off}/V_B	-1.0	-	+1.0	mV/V	
Operating Frequency	f_{max}	0	-	1	MHz	
Temp. Coeff. of offset voltage	TCV_{off}	-3	-	+3	($\mu\text{V/V}$)/K	$T_{amb} = -25$ to $+125^\circ\text{C}$
Temp. Coeff. Of bridge resistance	TCR_{br}	0.25	0.3	0.35	%/K	$T_{amb} = -25$ to $+125^\circ\text{C}$
Temp. Coeff. of open circuit sensitivity $V_B = 5\text{V}$	TCS_V	-0.25	-0.3	-0.35	%/K	$T_{amb} = -25$ to $+125^\circ\text{C}$
Temp. Coeff. of open circuit sensitivity $I_B = 3\text{mA}$	TCS_I	-	-0.1	-	%/K	$T_{amb} = -25$ to $+125^\circ\text{C}$

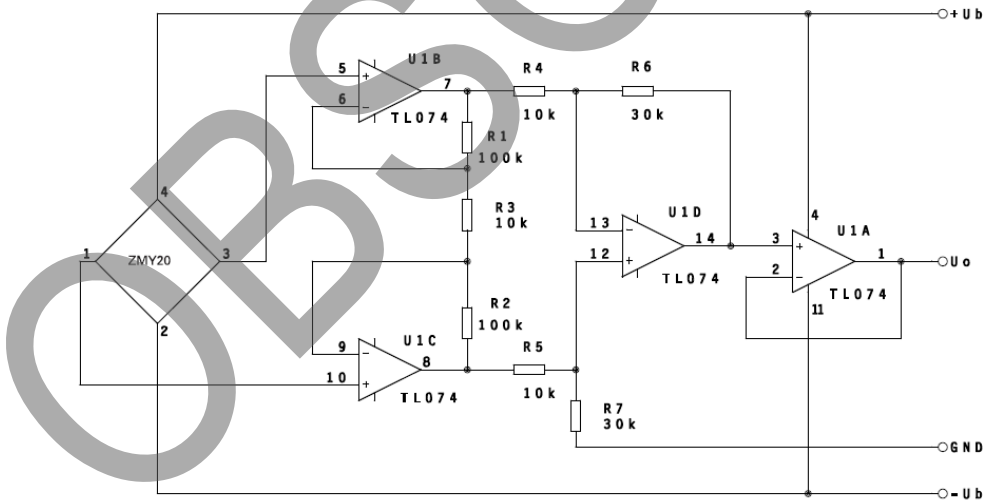
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Typical Applications Circuit

Application 1 (digital output)



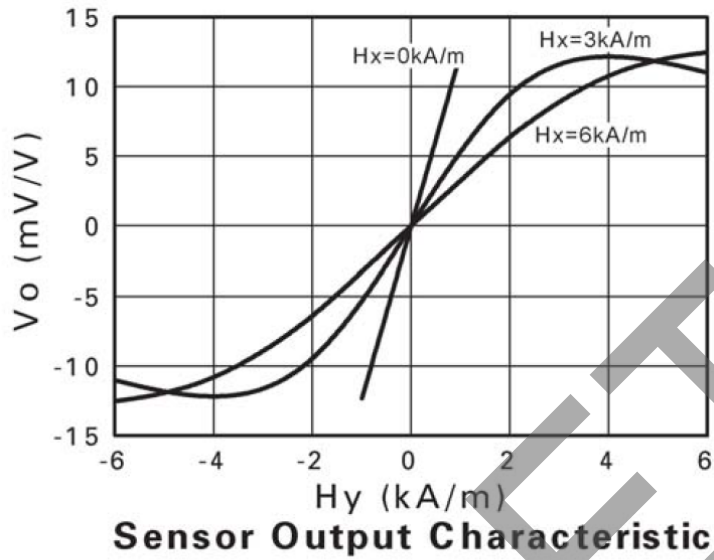
Application 2 (analog output)



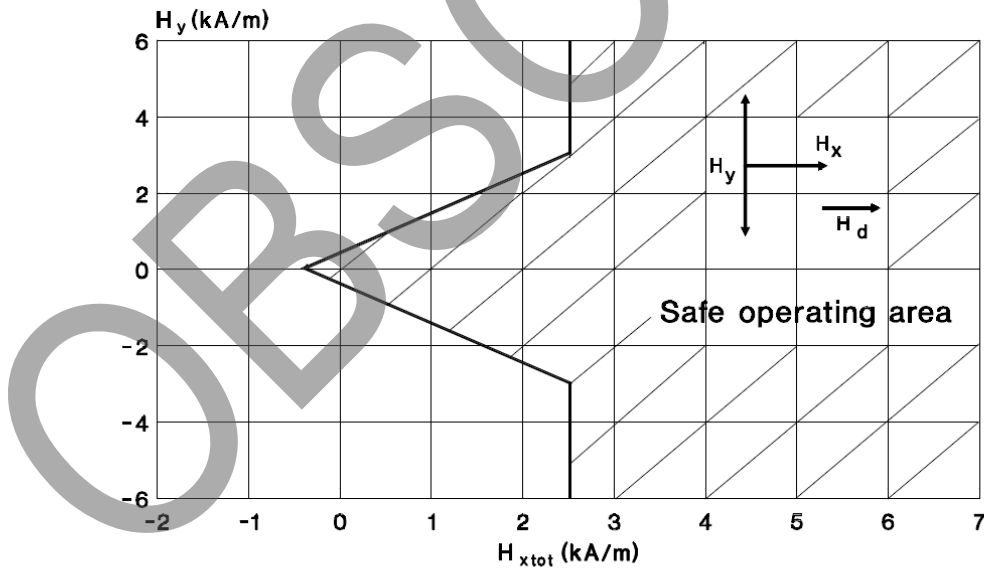
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Sensor output characteristic
 $V_O = f(H_y)$; H_x -parameter
 $V_b = \text{const}$; $T_{\text{amb}} = 25^\circ\text{C}$



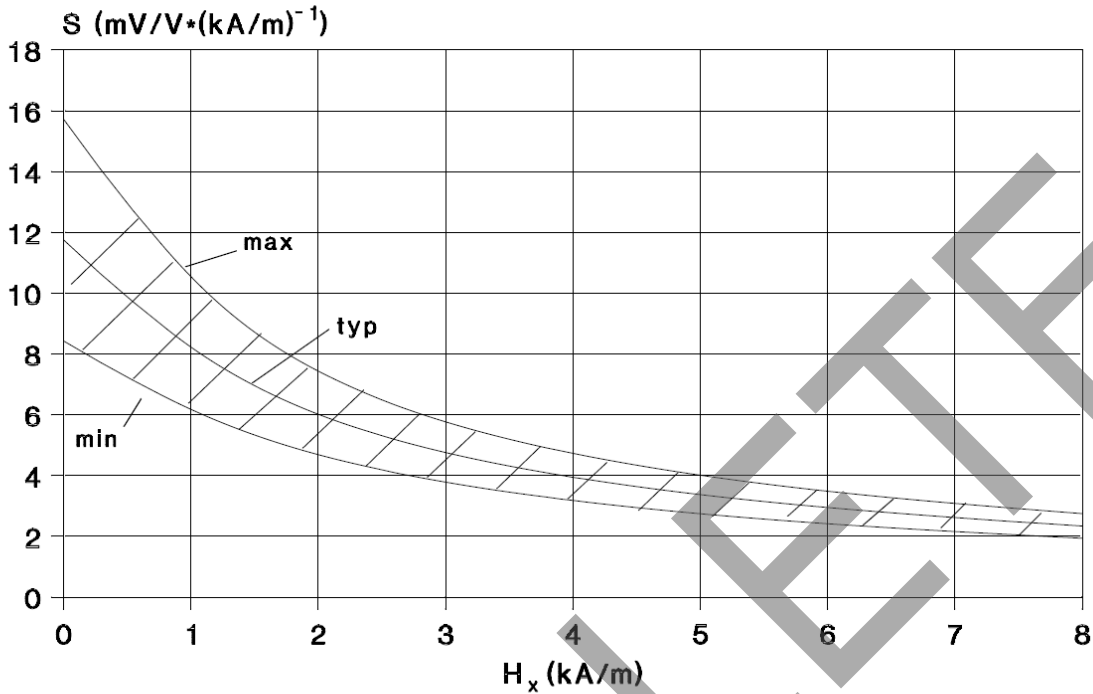
Safe operating area
 $H_{x\text{tot}} = H_x + H_d$; $T_{\text{amb}} = 25^\circ\text{C}$; (H_d =disturbing field)



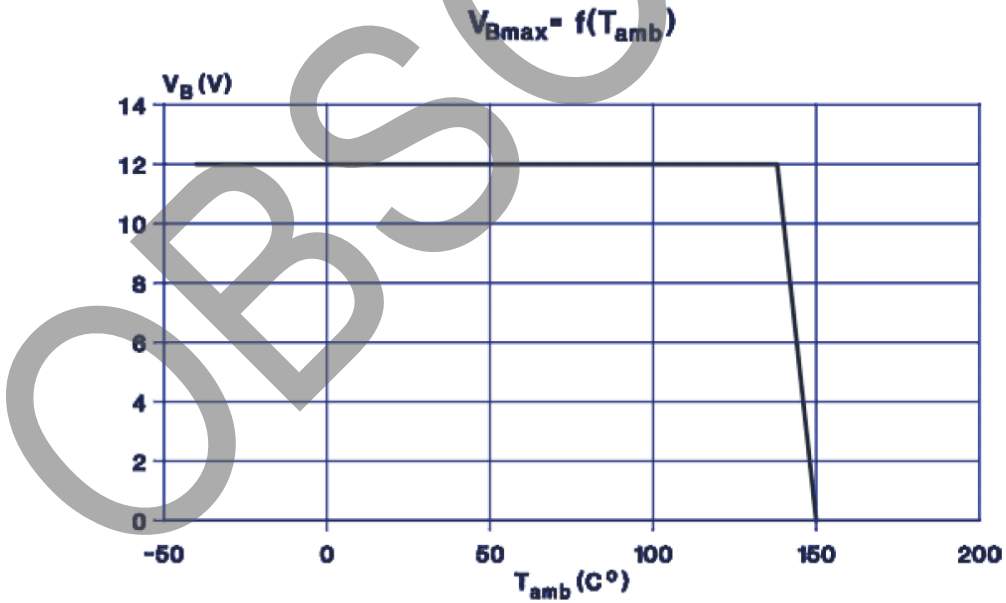
The sensor has to be reset after leaving the safe operating area by an auxiliary field of $H_x = 3 \text{ kA/m}$

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Sensor sensitivity characteristic
 $S=f(H_x)$
 $V_b=const; T_{amb}=25^{\circ}C$



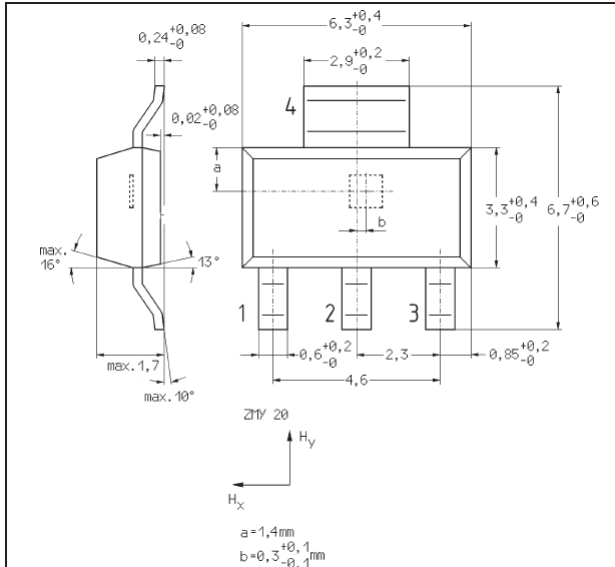
Supply voltage (maximum) derating curve
 $V_{Bmax}=f(T_{amb})$



Device mounted on 40 x 40 mm² board (copper area 600mm²)

Package Outline Dimensions

Please see <http://www.diodes.com/package-outlines.html> for the latest version.



CONTROLLING DIMENSIONS IN MILLIMETRES
APPROX CONVERSIONS INCHES.

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